

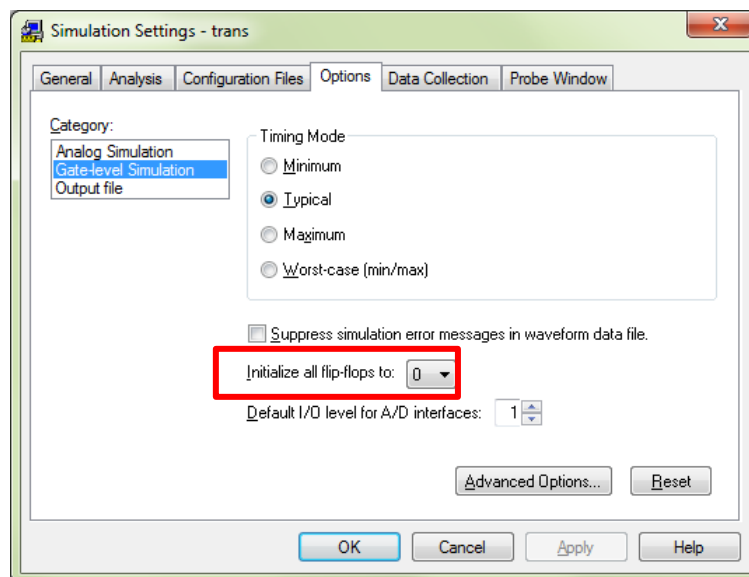
VIPER26K PSPICE Model Usage Instructions

The PSPICE model has been developed on OrCAD Capture v. 17.2. We recommend to use this version or higher to avoid convergence problems and speed up the simulation. The zip package contains two files:

- “VIPER26K.OLB”, the symbol to place in the schematic.
- “VIPER265K.LIB”, the library containing the real implementation of the model.
- “VIPER267K.LIB”, the library containing the real implementation of the model.

In order to use the model, create a new OrCAD project, add the VIPER26K.OLB

NOTE. Before starting the simulation, make sure that the option “Initialize all flip-flops” is set to “0”.



In case of convergence problems, check the option “AutoConverge”.

